

**Phy 556 HW 6, answer to problem 2 – vibrations of a 2-d square molecule AB<sub>4</sub>**

The potential energy is  $U=U_1 + U_2$ , where

$$U_1 = \frac{1}{2}K_1[(x_1 - x_0)^2 + (y_2 - y_0)^2 + (x_3 - x_0)^2 + (y_4 - y_0)^2]$$

$$U_2 = \frac{1}{4}K_2[(x_2 - y_2 - x_1 + y_1)^2 + (x_3 + y_3 - x_2 - y_2)^2 + (x_4 - y_4 - x_3 + y_3)^2 + (x_1 + y_1 - x_4 - y_4)^2]$$

Newton's laws are expressed with mass-weighted coordinates as  $\frac{d^2}{dt^2}|s\rangle = -\hat{D}|s\rangle$ , where

$\hat{D} = \hat{D}_1 + \hat{D}_2$  and the 10-vector and 10 x 10 matrices are

$$|s\rangle = \begin{pmatrix} \sqrt{M}x_0 \\ \sqrt{M}y_0 \\ \sqrt{m}x_1 \\ \sqrt{m}y_1 \\ \sqrt{m}x_2 \\ \sqrt{m}y_2 \\ \sqrt{m}x_3 \\ \sqrt{m}y_3 \\ \sqrt{m}x_4 \\ \sqrt{m}y_4 \end{pmatrix} \quad \hat{D}_1 = \frac{K_1}{\sqrt{mM}} \begin{pmatrix} 2r & 0 & -1 & 0 & 0 & 0 & -1 & 0 & 0 & 0 \\ 0 & 2r & 0 & 0 & 0 & -1 & 0 & 0 & 0 & -1 \\ -1 & 0 & 1/r & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 & 0 & 1/r & 0 & 0 & 0 & 0 \\ -1 & 0 & 0 & 0 & 0 & 0 & 1/r & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1/r \end{pmatrix} \quad \text{with } r = \sqrt{\frac{m}{M}}$$

$$\text{and } \hat{D}_2 = \frac{K_2}{2m} \begin{pmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & 0 & -1 & 1 & 0 & 0 & -1 & -1 \\ 0 & 0 & 0 & 2 & 1 & -1 & 0 & 0 & -1 & -1 \\ 0 & 0 & -1 & 1 & 2 & 0 & -1 & -1 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 & 2 & -1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & -1 & -1 & 2 & 0 & -1 & 1 \\ 0 & 0 & 0 & 0 & -1 & -1 & 0 & 2 & 1 & -1 \\ 0 & 0 & -1 & -1 & 0 & 0 & -1 & 1 & 2 & 0 \\ 0 & 0 & -1 & -1 & 0 & 0 & 1 & -1 & 0 & 2 \end{pmatrix}$$

The squared frequencies  $\omega^2$  are the eigenvalues of the full matrix  $\hat{D} = \hat{D}_1 + \hat{D}_2$ . Group theory tells us some of the eigenvectors. The character table for the group C<sub>4v</sub> is shown below to the left, and also, to the right, the numbering system for the four atoms of mass  $m$ . These atoms form a basis for the “permutation representation” which reduces to A<sub>1</sub>+B<sub>2</sub>+E. Basis functions for A<sub>1</sub> and B<sub>2</sub> are shown to the right in the top row, and for the E doublet, to the right in the bottom row. The specification B<sub>2</sub> (rather than B<sub>1</sub>) derives from an (arbitrary) choice that  $\sigma_v$  planes pass through atoms and  $\sigma_d$  planes pass between them.

$C_{4v}$	E	$2C_4$	$C_2$	$2\sigma_v$	$2\sigma_d$
$A_1$	+1	+1	+1	+1	+1
$A_2$	+1	+1	+1	-1	-1
$B_1$	+1	-1	+1	+1	-1
$B_2$	+1	-1	+1	-1	+1
E	+2	0	-2	0	0

The displacements of atoms ( $|u\rangle$ , like  $|s\rangle$  except without the mass factor) are the basis for the 10-dimensional representation which transforms like the direct product of the 2-vector with the permutation representation (of all 5 atoms). A 2-vector transforms like E. The central atom does not mix with the others under rotations, and thus is an  $A_1$  subspace. The displacements of the central atom thus transform as E. The other 8 degrees of freedom transform thus as  $E \times (A_1 + B_2 + E)$ . The representations  $E \times A_1$  and  $E \times B_2$  are both E representations, which consist of attaching x or y displacements to the atoms in the  $A_1$  and  $B_2$  patterns shown in the figure above. These E basis functions can be turned into normalized  $|s\rangle$ -vector basis functions most simply as follows

$$|x_1\rangle = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}, |x_2\rangle = \frac{1}{2} \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \\ 1 \\ 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{pmatrix}, \text{ and } |x_3\rangle = \frac{1}{2} \begin{pmatrix} 0 \\ 0 \\ 1 \\ -1 \\ 1 \\ 0 \\ 0 \\ 0 \\ -1 \\ 0 \end{pmatrix} \text{ and similar for } |y_1\rangle, |y_2\rangle, \text{ and } |y_3\rangle, \text{ except}$$

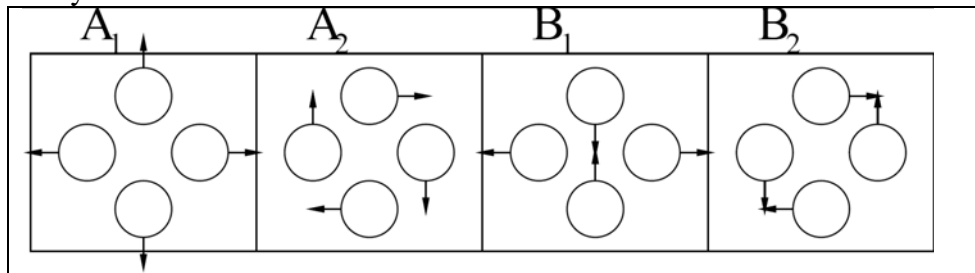
shifted down one entry to change x components into y components. The numbering 1,2,3 is arbitrary. If we take the 6 vectors just listed and compute  $\langle \alpha | \hat{D} | \beta \rangle$ , the resulting 6 x 6 matrix is guaranteed to block diagonalize into two identical 3 x 3 matrices, one for x components and one for y. But we can further simplify because we also are guaranteed that one eigenvector of each sub-block has eigenvalue 0 and corresponds to the uniform displacement in the x (or y) direction of the whole molecule. The uniform x-displacement is  $|x_0\rangle = \sqrt{M}|x_1\rangle + 2\sqrt{m}|x_2\rangle$ . It is easy to verify that both  $\hat{D}_1|x_0\rangle$  and  $\hat{D}_2|x_0\rangle$  are zero. We then need to choose two basis functions orthogonal to  $|x_0\rangle$ . The simplest choice is  $|x_\alpha\rangle = [2\sqrt{m}|x_1\rangle - \sqrt{M}|x_2\rangle] / \sqrt{M+4m}$  and  $|x_\beta\rangle = |x_3\rangle$ . Finally, we

compute the 2 x 2 matrices  $\langle x\alpha | \hat{D} | x\beta \rangle$  (the y-version is of course identical.) The answer is

$$[\hat{D}_1]_{E'x} = \frac{K_1}{2m} \begin{pmatrix} \frac{M+4m}{M} & -\sqrt{\frac{M+4m}{M}} \\ -\sqrt{\frac{M+4m}{M}} & 1 \end{pmatrix} \text{ and } [\hat{D}_2]_{E'x} = \frac{2K_2}{m} \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}.$$

Note that each of these two sub-systems has simple eigenvectors and one null eigenvalue. When the two spring constants  $K_1$  and  $K_2$  are both non-zero, the system is stable and the eigenvectors and eigenvalues are found by solving 2 x 2 matrices with no additional symmetry.

Finally, there are 4 more states belonging to  $E \times E = A_1 + A_2 + B_1 + B_2$ , involving only the 4 outer masses  $m$  (the central mass  $M$  is stationary.) It is easy to “guess” the eigenvectors, and assign symmetry labels by the transformation properties listed in the character table. The eigenvectors are shown pictorially, and can thus be constructed algebraically.



$$|A_1\rangle = \frac{1}{2} \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \\ 0 \\ 1 \\ -1 \\ 0 \\ 0 \\ -1 \end{pmatrix}, |A_2\rangle = \frac{1}{2} \begin{pmatrix} 0 \\ 0 \\ 0 \\ -1 \\ 1 \\ 0 \\ 0 \\ 1 \\ -1 \\ 0 \end{pmatrix}, |B_1\rangle = \frac{1}{2} \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \\ 0 \\ -1 \\ -1 \\ 0 \\ 0 \\ 1 \end{pmatrix}, |B_2\rangle = \frac{1}{2} \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 1 \\ 0 \\ 0 \\ -1 \\ -1 \\ 0 \end{pmatrix}$$

$A_2$  is a pure rotation with eigenvalue 0.  $A_1$  is an eigenvector of  $\hat{D}_1$  with eigenvalue  $K_1/m$ , and of  $\hat{D}_2$  with eigenvalue  $2K_2/m$ , so the frequency is  $\omega^2 = (K_1 + 2K_2)/m$ .  $B_1$  is an eigenvector of  $\hat{D}_1$  with eigenvalue  $K_1/m$ , and of  $\hat{D}_2$  with eigenvalue 0, so the frequency is  $\omega^2 = K_1/m$ .  $B_2$  is an eigenvector of  $\hat{D}_1$  with eigenvalue 0, and of  $\hat{D}_2$  with eigenvalue  $2K_2/m$ , so the frequency is  $\omega^2 = 2K_2/m$ .