The 2-body central force problem has Lagrangian (1)  $L = \frac{1}{2}\mu (\dot{r}^2 + r^2\dot{\phi}^2) - U(r)$ . This is the **real** Lagrangian. The version (2)  $L = \frac{1}{2}\mu \dot{r}^2 + \frac{M^2}{2\mu r^2} - U(r)$  is numerically correct, since  $M = \mu r^2 \dot{\phi}$  is conserved. [I switched from L to M as a symbol for angular momentum, since it is hard to find a script "L" to use for "Lagrangian."]

The time-independence of L means that (3)  $E = \sum_i \dot{q}_i \partial L/\partial \dot{q}_i - L$  is conserved, where  $q_i$  are **all** the generalized coordinates. These are  $(r,\phi)$ . In class I was seduced by the appearance of version (2) as a Lagrangian with one degree of freedom. It really has two degrees of freedom, but since M is conserved, for many purposes you can forget the  $\phi$  degree of freedom. But it is really there;  $\phi$  evolves in time. So when you use (3) to calculate E, you have to include both partial derivatives of L, not just one, as I foolishly thought by looking at (2). The result, of course, is

$$E = \frac{1}{2}\mu (\dot{r}^2 + r^2\dot{\phi}^2) + U(r) = \frac{1}{2}\mu \dot{r}^2 + \frac{M^2}{2\mu r^2} + U(r)$$